

Evoluten und Evolventen

(Anleitung zu einem Kleinprojekt)

Verwende die Ergebnisse des Kleinprojekts "Schläuche":

Rechnung

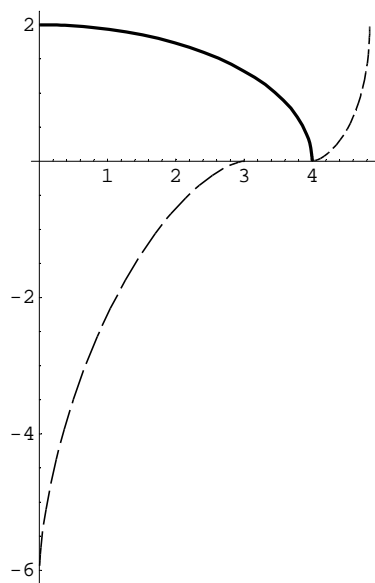
```
In[1]:= Remove["Global`*"];

In[2]:= from[uhu_] := Module[{}, (*Rechnung*)
  v[t_] := {x[t], y[t], 0};
  κ[t_] := Sqrt[((v''[t].v''[t]) (v'[t].v'[t]) - (v'[t].v''[t])^2) / ((v'[t]).(v'[t]))];
  ρ[t_] := 1/κ[t];
  tT[t_] := v'[t] / Sqrt[v'[t].v'[t]];
  nN[t_] := 1/κ[t] 1 / Sqrt[v'[t].v'[t]] D[v'[t] / Sqrt[v'[t].v'[t]], t];
  evolu[t_] := v[t] + ρ[t] nN[t] / Sqrt[nN[t].nN[t]];
  evolv[t_, anf_] := v[t] + (-1) tT[t] Evaluate[N[Integrate[Sqrt[v'[ti].v'[ti]], {ti,
  v2[t_] := {v[t][[1]], v[t][[2]]};
  evolu2[t_] := {evolu[t][[1]], evolu[t][[2]]};
  evolv2[t_, anf_] := {evolv[t, anf][[1]], evolv[t, anf][[2]]};
  (*Plot 3 D*)
  p1[anf_, end_] := ParametricPlot[Evaluate[v2[t]], {t, anf, end},
    AspectRatio → Automatic, PlotStyle → {Thickness[.01]}, DisplayFunction → Identity];
  p2[anf_, end_] := ParametricPlot[Evaluate[evolu2[t]], {t, anf, end}, AspectRatio → Automati
    PlotStyle → {Thickness[.005], Dashing[{0.1, 0.02}]}, DisplayFunction → Identity];
  p3[anf_, end_] := ParametricPlot[Evaluate[evolv2[t, anf]], {t, anf, end}, AspectRatio
    PlotStyle → {Thickness[.005], Dashing[{0.05, 0.015}]}, DisplayFunction → Identity];
  Show[
    p1[anf, end],
    p2[anf, end],
    p3[anf, end], DisplayFunction → $DisplayFunction];
]
```

Demos Kurvendefinitionen

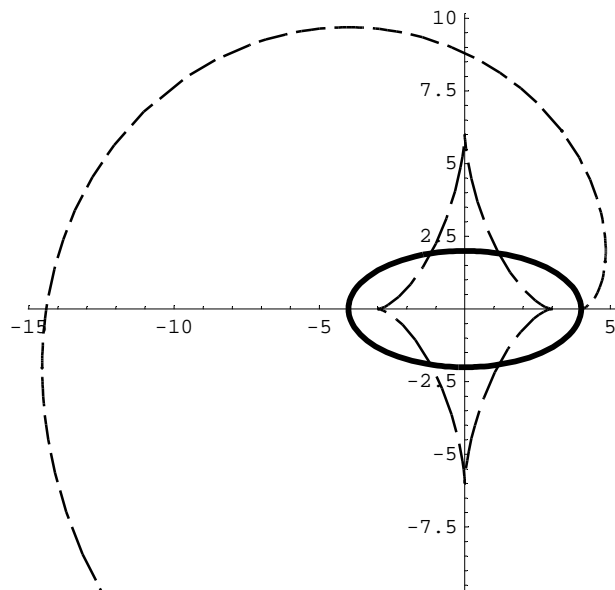
1

```
In[3]:= (*Kurvendefinitionen*)  
x[t_] := 4 Cos[t];  
y[t_] := 2 Sin[t];  
z[t_] := 0;  
anf = 0;  
end = Pi / 2;  
from[uhu];
```



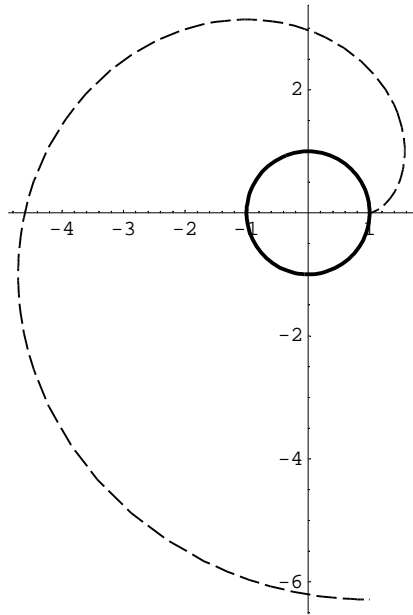
2

```
In[9]:= (*Kurvendefinitionen*)  
x[t_] := 4 Cos[t];  
y[t_] := 2 Sin[t];  
z[t_] := 0;  
anf = 0;  
end = 2 Pi;  
from[uhu];
```

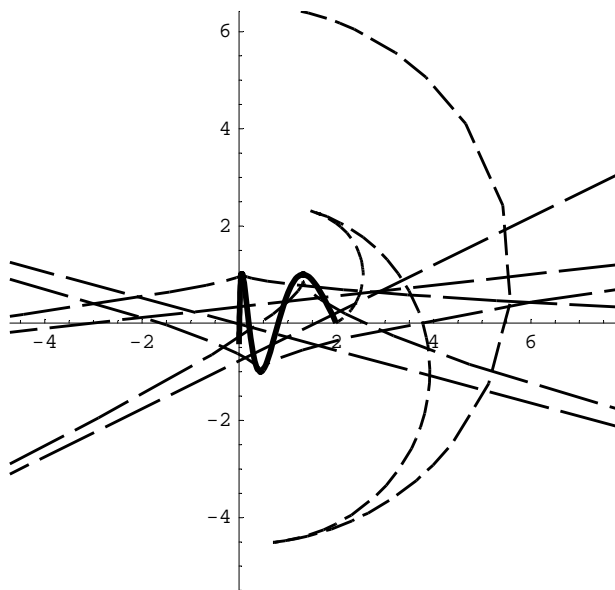


3

```
In[15]:= (*Kurvendefinitionen*)  
x[t_]:= Cos[t];  
y[t_]:= Sin[t];  
z[t_]:= 0;  
anf=0;  
end =2Pi;  
from[uhu];
```



```
In[22]:= (*Kurvendefinitionen*)  
x[t_]:= 1+Cos[t];  
y[t_]:= Sin[t^2];  
z[t_]:= 0;  
anf=0.1;  
end =Pi;  
from[uhu];
```



Ergebnisse von Untersuchungen der Klasse M2p: Schlauchdefinitionen für interessante Formen

In[29]:=

Rechnung mit Zwischenergebnissen

In[29]:= Remove["Global`*"];

```
In[30]:= from[uhu_] := Module[{}, (*Rechnung*)
  v[t_] := {x[t], y[t], 0};
  Print["v[t]  ", v[t]];
  κ[t_] := Sqrt[((v'[t].v'[t]) (v'[t].v'[t]) - (v'[t].v'[t])^2) / ((v'[t]).(v'[t])
  ρ[t_] := 1/κ[t];
  tT[t_] := v'[t] / Sqrt[v'[t].v'[t]];
  Print["tT[t]  ", tT[t]];
  nN[t_] := 1/κ[t] 1 / Sqrt[v'[t].v'[t]] D[v'[t] / Sqrt[v'[t].v'[t]], t];
  Print["nNT[t]  ", nN[t]];
  evolu[t_] := v[t] + ρ[t] nN[t] / Sqrt[nN[t].nN[t]];
  Print["evolu[t]  ", evolu[t]];
  evolv[t_, anf_] := v[t] + (-1) tT[t] Evaluate[N[Integrate[Sqrt[v'[ti].v'[ti]], {ti
  Print["evolv[t,anf]  ", evolv[t, anf]];
  v2[t_] := {v[t][[1]], v[t][[2]]};
  Print["v2[t]  ", v2[t]];
  evolu2[t_] := {evolu[t][[1]], evolu[t][[2]]};
  Print["evolu2[t]  ", evolu2[t]];
  evolv2[t_, anf_] := {evolv[t, anf][[1]], evolv[t, anf][[2]]};
  Print["evolv2[t,anf]  ", evolv2[t, anf]];
  (*Plot 3 D*)
  p1[anf_, end_] :=
    ParametricPlot[Evaluate[v2[t]], {t, anf, end}, AspectRatio → Automatic, PlotStyle
  p2[anf_, end_] := ParametricPlot[Evaluate[evolu2[t]], {t, anf, end},
    AspectRatio → Automatic, PlotStyle → {Thickness[.01], Dashing[{0.1, 0.02]}}];
  p3[anf_, end_] := ParametricPlot[Evaluate[evolv2[t, anf]], {t, anf, end},
    AspectRatio → Automatic, PlotStyle → {Thickness[.01], Dashing[{0.05, 0.015]}}]
  Show[
    p1[anf, end],
    p2[anf, end],
    p3[anf, end]
  ];
  (*Kurvendefinitionen*)
  x[t_] := 4 Cos[t];
  y[t_] := 2 Sin[t];
  z[t_] := 0;
  anf = 0;
  end = Pi;
  from[uhu];

v[t]  {4 Cos[t], 2 Sin[t], 0}
```


evolu2[t]

$$\left\{ 4 \operatorname{Cos}[t] + \left((4 \operatorname{Cos}[t]^2 + 16 \operatorname{Sin}[t]^2)^{5/2} \left(\frac{48 \operatorname{Cos}[t] \operatorname{Sin}[t]^2}{(4 \operatorname{Cos}[t]^2 + 16 \operatorname{Sin}[t]^2)^{3/2}} - \frac{4 \operatorname{Cos}[t]}{\sqrt{4 \operatorname{Cos}[t]^2 + 16 \operatorname{Sin}[t]^2}} \right) \right) \right\} /$$

$$\left((-144 \operatorname{Cos}[t]^2 \operatorname{Sin}[t]^2 + (16 \operatorname{Cos}[t]^2 + 4 \operatorname{Sin}[t]^2) (4 \operatorname{Cos}[t]^2 + 16 \operatorname{Sin}[t]^2)) \right.$$

$$\sqrt{\left(\frac{(4 \operatorname{Cos}[t]^2 + 16 \operatorname{Sin}[t]^2)^2 \left(-\frac{48 \operatorname{Cos}[t] \operatorname{Sin}[t]^2}{(4 \operatorname{Cos}[t]^2 + 16 \operatorname{Sin}[t]^2)^{3/2}} - \frac{4 \operatorname{Cos}[t]}{\sqrt{4 \operatorname{Cos}[t]^2 + 16 \operatorname{Sin}[t]^2}} \right)^2}{-144 \operatorname{Cos}[t]^2 \operatorname{Sin}[t]^2 + (16 \operatorname{Cos}[t]^2 + 4 \operatorname{Sin}[t]^2) (4 \operatorname{Cos}[t]^2 + 16 \operatorname{Sin}[t]^2)} + \right.$$

$$\left. \left. \frac{(4 \operatorname{Cos}[t]^2 + 16 \operatorname{Sin}[t]^2)^2 \left(-\frac{24 \operatorname{Cos}[t]^2 \operatorname{Sin}[t]}{(4 \operatorname{Cos}[t]^2 + 16 \operatorname{Sin}[t]^2)^{3/2}} - \frac{2 \operatorname{Sin}[t]}{\sqrt{4 \operatorname{Cos}[t]^2 + 16 \operatorname{Sin}[t]^2}} \right)^2}{-144 \operatorname{Cos}[t]^2 \operatorname{Sin}[t]^2 + (16 \operatorname{Cos}[t]^2 + 4 \operatorname{Sin}[t]^2) (4 \operatorname{Cos}[t]^2 + 16 \operatorname{Sin}[t]^2)} \right) \right) \right\},$$

$$2 \operatorname{Sin}[t] + \left((4 \operatorname{Cos}[t]^2 + 16 \operatorname{Sin}[t]^2)^{5/2} \left(-\frac{24 \operatorname{Cos}[t]^2 \operatorname{Sin}[t]}{(4 \operatorname{Cos}[t]^2 + 16 \operatorname{Sin}[t]^2)^{3/2}} - \frac{2 \operatorname{Sin}[t]}{\sqrt{4 \operatorname{Cos}[t]^2 + 16 \operatorname{Sin}[t]^2}} \right) \right) /$$

$$\left((-144 \operatorname{Cos}[t]^2 \operatorname{Sin}[t]^2 + (16 \operatorname{Cos}[t]^2 + 4 \operatorname{Sin}[t]^2) (4 \operatorname{Cos}[t]^2 + 16 \operatorname{Sin}[t]^2)) \right.$$

$$\sqrt{\left(\frac{(4 \operatorname{Cos}[t]^2 + 16 \operatorname{Sin}[t]^2)^2 \left(-\frac{48 \operatorname{Cos}[t] \operatorname{Sin}[t]^2}{(4 \operatorname{Cos}[t]^2 + 16 \operatorname{Sin}[t]^2)^{3/2}} - \frac{4 \operatorname{Cos}[t]}{\sqrt{4 \operatorname{Cos}[t]^2 + 16 \operatorname{Sin}[t]^2}} \right)^2}{-144 \operatorname{Cos}[t]^2 \operatorname{Sin}[t]^2 + (16 \operatorname{Cos}[t]^2 + 4 \operatorname{Sin}[t]^2) (4 \operatorname{Cos}[t]^2 + 16 \operatorname{Sin}[t]^2)} + \right.$$

$$\left. \left. \frac{(4 \operatorname{Cos}[t]^2 + 16 \operatorname{Sin}[t]^2)^2 \left(-\frac{24 \operatorname{Cos}[t]^2 \operatorname{Sin}[t]}{(4 \operatorname{Cos}[t]^2 + 16 \operatorname{Sin}[t]^2)^{3/2}} - \frac{2 \operatorname{Sin}[t]}{\sqrt{4 \operatorname{Cos}[t]^2 + 16 \operatorname{Sin}[t]^2}} \right)^2}{-144 \operatorname{Cos}[t]^2 \operatorname{Sin}[t]^2 + (16 \operatorname{Cos}[t]^2 + 4 \operatorname{Sin}[t]^2) (4 \operatorname{Cos}[t]^2 + 16 \operatorname{Sin}[t]^2)} \right) \right) \right\}$$

evol2[t,anf] $\left\{ 4 \operatorname{Cos}[t] + \frac{8 \cdot \operatorname{EllipticE}[t, -3.] \operatorname{Sin}[t]}{\sqrt{4 \operatorname{Cos}[t]^2 + 16 \operatorname{Sin}[t]^2}}, 2 \operatorname{Sin}[t] - \frac{4 \cdot \operatorname{Cos}[t] \operatorname{EllipticE}[t, -3.]}{\sqrt{4 \operatorname{Cos}[t]^2 + 16 \operatorname{Sin}[t]^2}} \right\}$

