

Inputs zu Lösungen

1

Literaturstudium

2

a Interpretation der Parameter: Angelegenheit der Physik oder der technischen Mechanik. Wichtig: Bei einer eindimensional gerichteten Bewegung kann z.B. m eine Masse bedeuten, d eine Dämpfungskonstante und k eine Federkonstante. Bei einer Drehbewegung wäre entsprechend Statt m das Massenträgheitsmoment I oder J zu setzen etc.

D wäre im ersten Fall eine auf die Feder und die Masse bezogenes Dämpfungsmass und ω_D eine Kreisfrequenz, welche in der Lösung erscheint.

b

1. Linke Seite transformieren, Anfangswerte anpassen

```
In[1]:= links = LaplaceTransform[m y''[t]+d y'[t]+k y[t],t,s] /.
  {LaplaceTransform[y[t],t,s]->Y[s],y[0]->y0,y'[0]->b}
```

```
Out[1]= k Y[s] + d (-y0 + s Y[s]) + m (-b - s y0 + s^2 Y[s])
```

2. Rechte Seite transformieren

```
In[2]:= rechts=LaplaceTransform[0 ,t,s]
```

```
Out[2]= 0
```

3. Gleichung links = rechts lösen

```
In[3]:= solv=Solve[links==rechts,{Y[s]}] // Flatten
```

```
Out[3]= {Y[s] ->  $\frac{b m + d y_0 + m s y_0}{k + d s + m s^2}$ }
```

4. Rücktransformation

```
In[4]:= U[s]:=Y[s]/. solv; U[s]
```

$$\text{Out[4]} = \frac{b m + d y_0 + m s y_0}{k + d s + m s^2}$$

```
In[5]:= U[s]//Apart
```

$$\text{Out[5]} = \frac{b m}{k + d s + m s^2} + \frac{(d + m s) y_0}{k + d s + m s^2}$$

```
In[6]:= u0[t_]:=InverseLaplaceTransform[U[s],s,t]//Simplify; u0[t]
```

$$\text{Out[6]} = \frac{1}{2 \sqrt{d^2 - 4 k m}} \left(e^{-\frac{(d + \sqrt{d^2 - 4 k m}) t}{2 m}} \left(2 b \left(-1 + e^{\frac{\sqrt{d^2 - 4 k m} t}{m}} \right) m + \left(d \left(-1 + e^{\frac{\sqrt{d^2 - 4 k m} t}{m}} \right) + \left(1 + e^{\frac{\sqrt{d^2 - 4 k m} t}{m}} \right) \sqrt{d^2 - 4 k m} \right) y_0 \right) \right)$$

(* Allgemeine Lösung bei freier Schwingung! *)

c

1. Linke Seite transformieren, Anfangswerte anpassen

```
In[7]:= links = LaplaceTransform[m y''[t]+d y'[t]+k y[t],t,s] /.
  {LaplaceTransform[y[t],t,s]->Y[s],y[0]->0,y'[0]->b}
```

$$\text{Out[7]} = k Y[s] + d s Y[s] + m (-b + s^2 Y[s])$$

2. Rechte Seite transformieren

```
In[8]:= rechts=LaplaceTransform[0 ,t,s]
```

$$\text{Out[8]} = 0$$

3. Gleichung links = rechts lösen

```
In[9]:= solv=Solve[links==rechts,{Y[s]}] // Flatten
```

$$\text{Out[9]} = \left\{ Y[s] \rightarrow \frac{b m}{k + d s + m s^2} \right\}$$

4. Rücktransformation

```
In[10]:= U[s]:=Y[s]/. solv; U[s]
```

$$\text{Out[10]} = \frac{b m}{k + d s + m s^2}$$

```
In[11]:= U[s]//Apart
```

$$\text{Out[11]} = \frac{b m}{k + d s + m s^2}$$

```
In[12]:= u0[t_]:=InverseLaplaceTransform[U[s],s,t]//Simplify; u0[t]
```

$$\text{Out[12]} = \frac{b e^{-\frac{(d+\sqrt{d^2-4km})t}{2m}} \left(-1 + e^{\frac{\sqrt{d^2-4km}t}{m}} \right) m}{\sqrt{d^2-4km}}$$

(* Allgemeine Lösung bei freier Schwingung! *)

d

1. Linke Seite transformieren, Anfangswerte anpassen

```
In[13]:= links = LaplaceTransform[1 y''[t]+1/2 y'[t]+1 y[t],t,s] /.
  {LaplaceTransform[y[t],t,s]->Y[s],y[0]->0,y'[0]->1}
```

$$\text{Out[13]} = -1 + Y[s] + \frac{1}{2} s Y[s] + s^2 Y[s]$$

2. Rechte Seite transformieren

```
In[14]:= rechts=LaplaceTransform[0 ,t,s]
```

```
Out[14]= 0
```

3. Gleichung links = rechts lösen

```
In[15]:= solv=Solve[links==rechts,{Y[s]}] // Flatten
```

$$\text{Out[15]} = \left\{ Y[s] \rightarrow \frac{2}{2 + s + 2 s^2} \right\}$$

4. Rücktransformation

```
In[16]:= U[s]:=Y[s]/. solv; U[s]
```

$$\text{Out[16]} = \frac{2}{2 + s + 2 s^2}$$

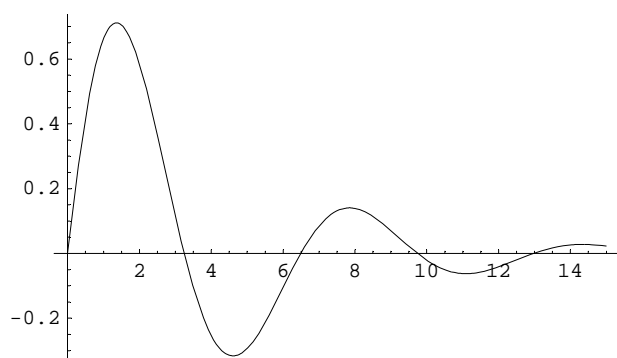
```
In[17]:= U[s]//Apart
```

$$\text{Out[17]} = \frac{2}{2 + s + 2 s^2}$$

```
In[18]:= u0[t_]:=InverseLaplaceTransform[U[s],s,t]//Simplify; u0[t]
```

$$\text{Out[18]} = \frac{4 e^{-t/4} \text{Sin}\left[\frac{\sqrt{15}t}{4}\right]}{\sqrt{15}}$$

```
In[19]:= Plot[u0[t],{t,0,15}];
```



e

1. Linke Seite transformieren, Anfangswerte anpassen

```
In[20]:= links = LaplaceTransform[1 y''[t]+1/2 y'[t]-1 y[t],t,s] /.
  {LaplaceTransform[y[t],t,s]→Y[s],y[0]→0,y'[0]→1}
```

```
Out[20]= -1 - Y[s] +  $\frac{1}{2}$  s Y[s] + s2 Y[s]
```

2. Rechte Seite transformieren

```
In[21]:= rechts=LaplaceTransform[0 ,t,s]
```

```
Out[21]= 0
```

3. Gleichung links = rechts lösen

```
In[22]:= solv=Solve[links==rechts,{Y[s]}] // Flatten
```

```
Out[22]= {Y[s] →  $\frac{2}{-2 + s + 2 s^2}$ }
```

4. Rücktransformation

```
In[23]:= U[s]:=Y[s]/. solv; U[s]
```

```
Out[23]=  $\frac{2}{-2 + s + 2 s^2}$ 
```

```
In[24]:= U[s]//Apart
```

```
Out[24]=  $\frac{2}{-2 + s + 2 s^2}$ 
```

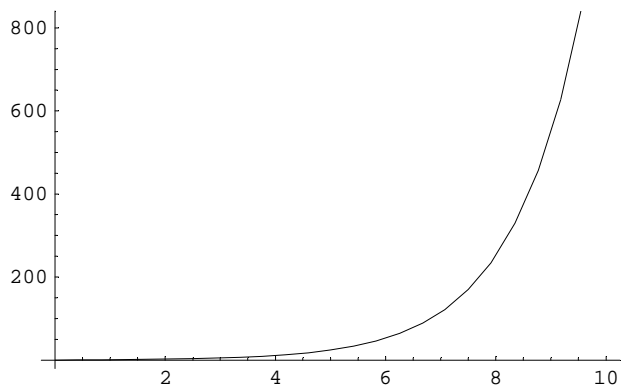
```
In[25]:= u0[t_]:=InverseLaplaceTransform[U[s],s,t]//Simplify; u0[t]
```

```
Out[25]=  $\frac{2 e^{-\frac{1}{4} (1+\sqrt{17}) t} \left(-1 + e^{\frac{\sqrt{17} t}{2}}\right)}{\sqrt{17}}$ 
```

```
In[26]:= u0[t]//Expand//N
```

```
Out[26]= -0.485071 2.71828-1.28078 t + 0.485071 2.718280.780776 t
```

```
In[27]:= Plot[u0[t],{t,0,10}];
```



```
In[28]:= (* ==> Explosion *)
```

f

1. Linke Seite transformieren, Anfangswerte anpassen

```
In[29]:= links = LaplaceTransform[m y''[t]+d y'[t]+k y[t],t,s] /.
  {LaplaceTransform[y[t],t,s]->Y[s],y[0]->0,y'[0]->0}
```

```
Out[29]= k Y[s] + d s Y[s] + m s2 Y[s]
```

2. Rechte Seite transformieren

```
In[30]:= rechts=LaplaceTransform[DiracDelta[t] ,t,s]
```

```
Out[30]= 1
```

3. Gleichung links = rechts lösen

```
In[31]:= solv=Solve[links==rechts,{Y[s]}] // Flatten
```

```
Out[31]= {Y[s] ->  $\frac{1}{k + d s + m s^2}$ }
```

4. Rücktransformation

```
In[32]:= U[s]:=Y[s]/. solv; U[s]
```

```
Out[32]=  $\frac{1}{k + d s + m s^2}$ 
```

```
In[33]:= U[s]//Apart
```

```
Out[33]=  $\frac{1}{k + d s + m s^2}$ 
```

```
In[34]:= u0[t_]:=InverseLaplaceTransform[U[s],s,t]//Simplify; u0[t]
```

$$\text{Out[34]} = \frac{e^{-\frac{(d+\sqrt{d^2-4km})t}{2m}} \left(-1 + e^{\frac{\sqrt{d^2-4km}t}{m}} \right)}{\sqrt{d^2-4km}}$$

g

1. Linke Seite transformieren, Anfangswerte anpassen

```
In[35]:= links = LaplaceTransform[1 y''[t]+1/2 y'[t]+1 y[t],t,s] /.
  {LaplaceTransform[y[t],t,s]->Y[s],y[0]->0,y'[0]->0}
```

$$\text{Out[35]} = Y[s] + \frac{1}{2} s Y[s] + s^2 Y[s]$$

2. Rechte Seite transformieren

```
In[36]:= rechts=LaplaceTransform[DiracDelta[t] ,t,s]
```

```
Out[36]= 1
```

3. Gleichung links = rechts lösen

```
In[37]:= solv=Solve[links==rechts,{Y[s]}] // Flatten
```

$$\text{Out[37]} = \left\{ Y[s] \rightarrow \frac{2}{2+s+2s^2} \right\}$$

4. Rücktransformation

```
In[38]:= U[s]:=Y[s]/. solv; U[s]
```

$$\text{Out[38]} = \frac{2}{2+s+2s^2}$$

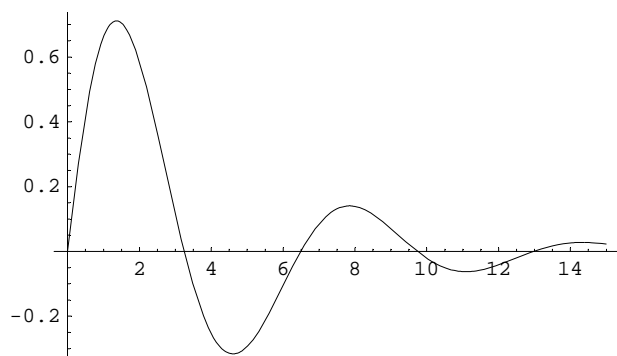
```
In[39]:= U[s]//Apart
```

$$\text{Out[39]} = \frac{2}{2+s+2s^2}$$

```
In[40]:= u0[t_]:=InverseLaplaceTransform[U[s],s,t]//Simplify; u0[t]
```

$$\text{Out[40]} = \frac{4 e^{-t/4} \text{Sin}\left[\frac{\sqrt{15}t}{4}\right]}{\sqrt{15}}$$

```
In[41]:= Plot[u0[t],{t,0,15}];
```



h

1. Linke Seite transformieren, Anfangswerte anpassen

```
In[42]:= links = LaplaceTransform[m y''[t]+d y'[t]+k y[t],t,s] /.
  {LaplaceTransform[y[t],t,s]->Y[s],y[0]->0,y'[0]->0}
```

```
Out[42]= k Y[s] + d s Y[s] + m s^2 Y[s]
```

2. Rechte Seite transformieren

```
In[43]:= rechts=LaplaceTransform[A Sin[ω t+ φ] ,t,s]
```

```
Out[43]= 
$$\frac{A (\sqrt{\omega^2} \cos[\varphi] \text{Sign}[\omega] + s \sin[\varphi])}{s^2 + \omega^2}$$

```

3. Gleichung links = rechts lösen

```
In[44]:= solv=Solve[links==rechts,{Y[s]}] // Flatten
```

```
Out[44]= {Y[s] -> 
$$\frac{A (\sqrt{\omega^2} \cos[\varphi] \text{Sign}[\omega] + s \sin[\varphi])}{(k + d s + m s^2) (s^2 + \omega^2)}$$
}
```

4. Rücktransformation

```
In[45]:= U1[s]:=Y[s]/. solv; U1[s]
```

```
Out[45]= 
$$\frac{A (\sqrt{\omega^2} \cos[\varphi] \text{Sign}[\omega] + s \sin[\varphi])}{(k + d s + m s^2) (s^2 + \omega^2)}$$

```

```
In[46]:= U[s]:=(U1[s]//Apart)/.Sign[ω]->1
```

```
In[47]:= u0[t_]:=InverseLaplaceTransform[U[s],s,t]//Simplify; u0[t]
```

$$\text{Out[47]} = \left(A e^{-\frac{(d+\sqrt{d^2-4km})t}{2m}} \left(\omega \sin[\varphi] \left(dk - d e^{\frac{\sqrt{d^2-4km}t}{m}} k - k \sqrt{d^2-4km} - e^{\frac{\sqrt{d^2-4km}t}{m}} k \sqrt{d^2-4km} + dm\omega^2 - d e^{\frac{\sqrt{d^2-4km}t}{m}} m\omega^2 + m\sqrt{d^2-4km}\omega^2 + e^{\frac{\sqrt{d^2-4km}t}{m}} m\sqrt{d^2-4km}\omega^2 - 2 e^{\frac{(d+\sqrt{d^2-4km})t}{2m}} \sqrt{d^2-4km} (-k+m\omega^2) \cos[t\omega] + 2 d e^{\frac{(d+\sqrt{d^2-4km})t}{2m}} \sqrt{d^2-4km}\omega \sin[t\omega] \right) + \sqrt{\omega^2} \cos[\varphi] \right) \right. \\ \left. \left(\omega \left(d^2 \left(-1 + e^{\frac{\sqrt{d^2-4km}t}{m}} \right) + d \left(1 + e^{\frac{\sqrt{d^2-4km}t}{m}} \right) \sqrt{d^2-4km} + 2 \left(-1 + e^{\frac{\sqrt{d^2-4km}t}{m}} \right) m(-k+m\omega^2) \right) - 2 d e^{\frac{(d+\sqrt{d^2-4km})t}{2m}} \sqrt{d^2-4km}\omega \cos[t\omega] - 2 e^{\frac{(d+\sqrt{d^2-4km})t}{2m}} \sqrt{d^2-4km}(-k+m\omega^2) \sin[t\omega] \right) \right) \right) / \\ (2\sqrt{d^2-4km}\omega(k^2+d^2\omega^2-2km\omega^2+m^2\omega^4))$$

i

1. Linke Seite transformieren, Anfangswerte anpassen

```
In[48]:= links = LaplaceTransform[m y''[t]+d y'[t]+k y[t],t,s] /.
{LaplaceTransform[y[t],t,s]->Y[s],y[0]->0,y'[0]->0}
```

```
Out[48]= k Y[s] + d s Y[s] + m s^2 Y[s]
```

2. Rechte Seite transformieren

```
In[49]:= rechts=LaplaceTransform[A Sin[omega t] ,t,s]
```

```
Out[49]= \frac{A \sqrt{\omega^2} \text{Sign}[\omega]}{s^2 + \omega^2}
```

3. Gleichung links = rechts lösen

```
In[50]:= solv=Solve[links==rechts,{Y[s]}] // Flatten
```

```
Out[50]= {Y[s] -> \frac{A \sqrt{\omega^2} \text{Sign}[\omega]}{(k + d s + m s^2) (s^2 + \omega^2)}}
```

4. Rücktransformation

```
In[51]:= U1[s]:=Y[s]/. solv; U1[s]
```

```
Out[51]= \frac{A \sqrt{\omega^2} \text{Sign}[\omega]}{(k + d s + m s^2) (s^2 + \omega^2)}
```

```
In[52]:= U[s]:=(U1[s]//Apart)/.Sign[omega]->1
```


In[53]:= u0[t_]:=InverseLaplaceTransform[U[s],s,t]//Simplify; u0[t]

$$\text{Out[53]} = \left(A \sqrt{\omega^2} \left(\frac{1}{\sqrt{d^2 - 4 k m}} \left(e^{-\frac{(d+\sqrt{d^2-4km})t}{2m}} \left(d^2 \left(-1 + e^{\frac{\sqrt{d^2-4km}t}{m}} \right) + d \left(1 + e^{\frac{\sqrt{d^2-4km}t}{m}} \right) \sqrt{d^2 - 4 k m} + 2 \left(-1 + e^{\frac{\sqrt{d^2-4km}t}{m}} \right) m (-k + m \omega^2) \right) \right) + 2 \left(-d \text{Cos}[t \omega] + \frac{(k - m \omega^2) \text{Sin}[t \omega]}{\omega} \right) \right) \right) / (2 (k^2 + d^2 \omega^2 - 2 k m \omega^2 + m^2 \omega^4))$$

In[54]:= u0[t]//Expand

$$\begin{aligned} \text{Out[54]} = & \frac{A d e^{-\frac{(d+\sqrt{d^2-4km})t}{2m}} \sqrt{\omega^2}}{2 (k^2 + d^2 \omega^2 - 2 k m \omega^2 + m^2 \omega^4)} + \frac{A d e^{\frac{\sqrt{d^2-4km}t}{m} - \frac{(d+\sqrt{d^2-4km})t}{2m}} \sqrt{\omega^2}}{2 (k^2 + d^2 \omega^2 - 2 k m \omega^2 + m^2 \omega^4)} - \\ & \frac{A d^2 e^{-\frac{(d+\sqrt{d^2-4km})t}{2m}} \sqrt{\omega^2}}{2 \sqrt{d^2 - 4 k m} (k^2 + d^2 \omega^2 - 2 k m \omega^2 + m^2 \omega^4)} + \frac{A d^2 e^{\frac{\sqrt{d^2-4km}t}{m} - \frac{(d+\sqrt{d^2-4km})t}{2m}} \sqrt{\omega^2}}{2 \sqrt{d^2 - 4 k m} (k^2 + d^2 \omega^2 - 2 k m \omega^2 + m^2 \omega^4)} + \\ & \frac{A e^{-\frac{(d+\sqrt{d^2-4km})t}{2m}} k m \sqrt{\omega^2}}{\sqrt{d^2 - 4 k m} (k^2 + d^2 \omega^2 - 2 k m \omega^2 + m^2 \omega^4)} - \frac{A e^{\frac{\sqrt{d^2-4km}t}{m} - \frac{(d+\sqrt{d^2-4km})t}{2m}} k m \sqrt{\omega^2}}{\sqrt{d^2 - 4 k m} (k^2 + d^2 \omega^2 - 2 k m \omega^2 + m^2 \omega^4)} - \\ & \frac{A e^{-\frac{(d+\sqrt{d^2-4km})t}{2m}} m^2 (\omega^2)^{3/2}}{\sqrt{d^2 - 4 k m} (k^2 + d^2 \omega^2 - 2 k m \omega^2 + m^2 \omega^4)} + \frac{A e^{\frac{\sqrt{d^2-4km}t}{m} - \frac{(d+\sqrt{d^2-4km})t}{2m}} m^2 (\omega^2)^{3/2}}{\sqrt{d^2 - 4 k m} (k^2 + d^2 \omega^2 - 2 k m \omega^2 + m^2 \omega^4)} - \\ & \frac{A d \sqrt{\omega^2} \text{Cos}[t \omega]}{k^2 + d^2 \omega^2 - 2 k m \omega^2 + m^2 \omega^4} + \frac{A k \sqrt{\omega^2} \text{Sin}[t \omega]}{\omega (k^2 + d^2 \omega^2 - 2 k m \omega^2 + m^2 \omega^4)} - \frac{A m \omega \sqrt{\omega^2} \text{Sin}[t \omega]}{k^2 + d^2 \omega^2 - 2 k m \omega^2 + m^2 \omega^4} \end{aligned}$$

j

1. Linke Seite transformieren, Anfangswerte anpassen

In[55]:= links = LaplaceTransform[1 y''[t]+d y'[t]+k y[t],t,s] /.
{LaplaceTransform[y[t],t,s]→Y[s],y[0]→0,y'[0]→0}

Out[55]= k Y[s] + d s Y[s] + s² Y[s]

2. Rechte Seite transformieren

In[56]:= rechts=LaplaceTransform[A Sin[ω t] ,t,s]

Out[56]= $\frac{A \sqrt{\omega^2} \text{Sign}[\omega]}{s^2 + \omega^2}$

3. Gleichung links = rechts lösen

In[57]:= solv=Solve[links==rechts,{Y[s]}] // Flatten

Out[57]= $\left\{ Y[s] \rightarrow \frac{A \sqrt{\omega^2} \text{Sign}[\omega]}{(k + d s + s^2) (s^2 + \omega^2)} \right\}$

4. Rücktransformation

In[58]:= `U1[s]:=Y[s]/. solv; U1[s]`

$$\text{Out}[58]= \frac{A \sqrt{\omega^2} \text{Sign}[\omega]}{(k + d s + s^2) (s^2 + \omega^2)}$$

In[59]:= `U[s]:=(U1[s]//Apart)/.Sign[\omega]->1`

In[60]:= `u0[t_]:=InverseLaplaceTransform[U[s],s,t]//Simplify; u0[t]`

$$\text{Out}[60]= \left(A \sqrt{\omega^2} \left(\frac{1}{\sqrt{d^2 - 4k}} \left(e^{-\frac{1}{2} (d + \sqrt{d^2 - 4k}) t} \right. \right. \right. \\ \left. \left. \left(d^2 (-1 + e^{\sqrt{d^2 - 4k} t}) + d (1 + e^{\sqrt{d^2 - 4k} t}) \sqrt{d^2 - 4k} - 2 (-1 + e^{\sqrt{d^2 - 4k} t}) (k - \omega^2) \right) \right) \right) + \\ \left. 2 \left(-d \text{Cos}[t \omega] + \frac{(k - \omega^2) \text{Sin}[t \omega]}{\omega} \right) \right) / (2 (k^2 + d^2 \omega^2 - 2 k \omega^2 + \omega^4))$$

In[61]:= `(* Formel problematisch für 4 k = d^2 (0 im Nenner)! *)`

k

1. Linke Seite transformieren, Anfangswerte anpassen

In[62]:= `links = LaplaceTransform[1 y''[t]+d y'[t]+k y[t],t,s] /.
{LaplaceTransform[y[t],t,s]->Y[s],y[0]->0,y'[0]->0,d->2 Sqrt[k]}`

$$\text{Out}[62]= k Y[s] + 2 \sqrt{k} s Y[s] + s^2 Y[s]$$

2. Rechte Seite transformieren

In[63]:= `rechts=LaplaceTransform[A Sin[\omega t] ,t,s]`

$$\text{Out}[63]= \frac{A \sqrt{\omega^2} \text{Sign}[\omega]}{s^2 + \omega^2}$$

3. Gleichung links = rechts lösen

In[64]:= `solv=Solve[links==rechts,{Y[s]}] // Flatten`

$$\text{Out}[64]= \left\{ Y[s] \rightarrow \frac{A \sqrt{\omega^2} \text{Sign}[\omega]}{(\sqrt{k} + s)^2 (s^2 + \omega^2)} \right\}$$

4. Rücktransformation

In[65]:= `U1[s]:=Y[s]/. solv; U1[s]`

$$\text{Out}[65]= \frac{A \sqrt{\omega^2} \text{Sign}[\omega]}{(\sqrt{k} + s)^2 (s^2 + \omega^2)}$$

In[66]:= `U[s]:=(U1[s]//Apart)/.Sign[\omega]->1`

In[67]:= `u0[t_]:=InverseLaplaceTransform[U[s],s,t]//Simplify; u0[t]/.d->2 Sqrt[k]`

$$\text{Out[67]} = \frac{A \sqrt{\omega^2} \left(2 e^{-\sqrt{k} t} \sqrt{k} + e^{-\sqrt{k} t} t (k + \omega^2) - 2 \sqrt{k} \text{Cos}[t \omega] + \frac{(k - \omega^2) \text{Sin}[t \omega]}{\omega} \right)}{(k + \omega^2)^2}$$

l, m

In[68]:= `solv=Solve[\omega^4+(d^2-2 k)\omega^2+k^2==0,{\omega}]//Simplify //Flatten`

$$\text{Out[68]} = \left\{ \omega \rightarrow -\sqrt{-\frac{d^2}{2} + \frac{1}{2} d \sqrt{d^2 - 4k} + k}, \omega \rightarrow \sqrt{-\frac{d^2}{2} + \frac{1}{2} d \sqrt{d^2 - 4k} + k}, \right. \\ \left. \omega \rightarrow -\sqrt{-\frac{d^2}{2} - \frac{1}{2} d \sqrt{d^2 - 4k} + k}, \omega \rightarrow \sqrt{-\frac{d^2}{2} - \frac{1}{2} d \sqrt{d^2 - 4k} + k} \right\}$$

In[69]:= `solv[[3]]`

$$\text{Out[69]} = \omega \rightarrow -\sqrt{-\frac{d^2}{2} - \frac{1}{2} d \sqrt{d^2 - 4k} + k}$$

In[70]:= `\omega e1[\epsilon_] := \omega + \epsilon /. solv[[1]]; \omega e1[\epsilon]`

$$\text{Out[70]} = -\sqrt{-\frac{d^2}{2} + \frac{1}{2} d \sqrt{d^2 - 4k} + k} + \epsilon$$

In[71]:= `\omega e2[\epsilon_] := \omega + \epsilon /. solv[[2]]; \omega e2[\epsilon]`

$$\text{Out[71]} = \sqrt{-\frac{d^2}{2} + \frac{1}{2} d \sqrt{d^2 - 4k} + k} + \epsilon$$

In[72]:= `(* Fall mit den meisten positiven Anteilen unter Wurzeln *)`

In[73]:= `\omega e2[0]//FullSimplify`

$$\text{Out[73]} = \sqrt{\frac{1}{2} d (-d + \sqrt{d^2 - 4k}) + k}$$

In[74]:= `\omega e2[0]//FullSimplify//InputForm`

$$\text{Out[74]} // \text{InputForm} = \text{Sqrt}[(d*(-d + \text{Sqrt}[d^2 - 4*k]))/2 + k]$$

In[75]:= `(* (d*(-d + Sqrt[d^2 - 4*k]))/2 ist für positive k negativ *)`

In[76]:= `Solve[(d*(-d + Sqrt[d^2 - 4*k]))/2 + k == 0,{k}]`

$$\text{Out[76]} = \{\{k \rightarrow 0\}\}$$

In[77]:= `(* \omega e2[0] ist daher nie positiv *)`

In[78]:= `\omega e2[0]/Sqrt[d^2]//PowerExpand`

$$\text{Out[78]} = \frac{\sqrt{-\frac{d^2}{2} + \frac{1}{2} d \sqrt{d^2 - 4k} + k}}{d}$$

```
In[79]:= ωε3[ε_]:=ω+ε/.solv[[3]]; ωε3[ε]
```

$$\text{Out}[79]= -\sqrt{-\frac{d^2}{2} - \frac{1}{2} d \sqrt{d^2 - 4k} + k} + \epsilon$$

```
In[80]:= ωε4[ε_]:=ω+ε/.solv[[4]]; ωε4[ε]
```

$$\text{Out}[80]= \sqrt{-\frac{d^2}{2} - \frac{1}{2} d \sqrt{d^2 - 4k} + k} + \epsilon$$

n

1. Linke Seite transformieren, Anfangswerte anpassen

```
In[81]:= links = LaplaceTransform[1 y''[t]+ 2q y'[t]+ω0^2 y[t],t,s] /.
  {LaplaceTransform[y[t],t,s]→Y[s],y[0]→1,y'[0]→0}
```

$$\text{Out}[81]= -s + s^2 Y[s] + \omega_0^2 Y[s] + 2q (-1 + s Y[s])$$

2. Rechte Seite transformieren

```
In[82]:= rechts=LaplaceTransform[0 ,t,s]
```

$$\text{Out}[82]= 0$$

3. Gleichung links = rechts lösen

```
In[83]:= solv=Solve[links==rechts,{Y[s]}] // Flatten
```

$$\text{Out}[83]= \left\{ Y[s] \rightarrow \frac{2q + s}{2qs + s^2 + \omega_0^2} \right\}$$

4. Rücktransformation

```
In[84]:= U1[s]:=Y[s]/. solv; U1[s]
```

$$\text{Out}[84]= \frac{2q + s}{2qs + s^2 + \omega_0^2}$$

```
In[85]:= U[s]:=(U1[s]//Apart)/.Sign[ω]->1
```

```
In[86]:= u0[t_]:=InverseLaplaceTransform[U[s],s,t]//Simplify; u0[t]/.d->2 Sqrt[k]
```

$$\text{Out}[86]= \frac{e^{-t(q + \sqrt{q^2 - \omega_0^2})} \left((-1 + e^{2t\sqrt{q^2 - \omega_0^2}}) q + (1 + e^{2t\sqrt{q^2 - \omega_0^2}}) \sqrt{q^2 - \omega_0^2} \right)}{2\sqrt{q^2 - \omega_0^2}}$$

o1

1. Linke Seite transformieren, Anfangswerte anpassen

```
In[87]:= links = LaplaceTransform[1 y''[t]+ 2q y'[t]+ω0^2 y[t],t,s] /.
  {LaplaceTransform[y[t],t,s]→Y[s],y[0]→1,y'[0]→0,q→1, ω0→1/2}
```

```
Out[87]= -s +  $\frac{Y[s]}{4}$  + s2 Y[s] + 2 (-1 + s Y[s])
```

2. Rechte Seite transformieren

```
In[88]:= rechts=LaplaceTransform[0 ,t,s]
```

```
Out[88]= 0
```

3. Gleichung links = rechts lösen

```
In[89]:= solv=Solve[links==rechts,{Y[s]}] // Flatten
```

```
Out[89]= {Y[s] →  $\frac{4 (2 + s)}{1 + 8 s + 4 s^2}$ }
```

4. Rücktransformation

```
In[90]:= U1[s]:=Y[s]/. solv; U1[s]
```

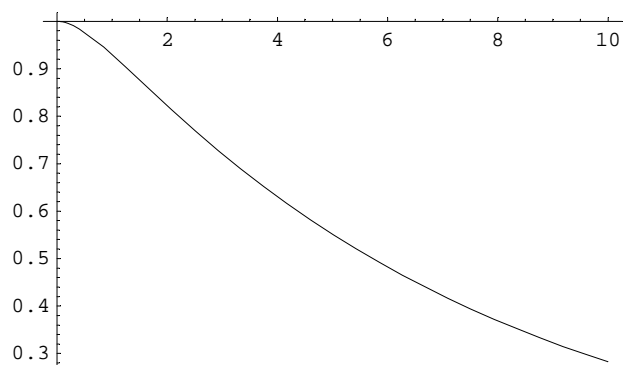
```
Out[90]=  $\frac{4 (2 + s)}{1 + 8 s + 4 s^2}$ 
```

```
In[91]:= U[s]:=(U1[s]//Apart)/.Sign[ω]->1
```

```
In[92]:= u0[t_]:=InverseLaplaceTransform[U[s],s,t]//Simplify; u0[t]
```

```
Out[92]=  $\frac{1}{6} e^{-\frac{1}{2} (2+\sqrt{3}) t} (3 - 2 \sqrt{3} + (3 + 2 \sqrt{3}) e^{\sqrt{3} t})$ 
```

```
In[93]:= Plot[u0[t],{t,0,10}];
```



o2

1. Linke Seite transformieren, Anfangswerte anpassen

```
In[94]:= links = LaplaceTransform[1 y''[t]+ 2q y'[t]+ω0^2 y[t],t,s] /.
  {LaplaceTransform[y[t],t,s]→Y[s],y[0]→1,y'[0]→0,q→1, ω0→1}
```

```
Out[94]= -s + Y[s] + s^2 Y[s] + 2 (-1 + s Y[s])
```

2. Rechte Seite transformieren

```
In[95]:= rechts=LaplaceTransform[0 ,t,s]
```

```
Out[95]= 0
```

3. Gleichung links = rechts lösen

```
In[96]:= solv=Solve[links==rechts,{Y[s]}] // Flatten
```

```
Out[96]= {Y[s] →  $\frac{2 + s}{(1 + s)^2}$ }
```

4. Rücktransformation

```
In[97]:= U1[s]:=Y[s]/. solv; U1[s]
```

```
Out[97]=  $\frac{2 + s}{(1 + s)^2}$ 
```

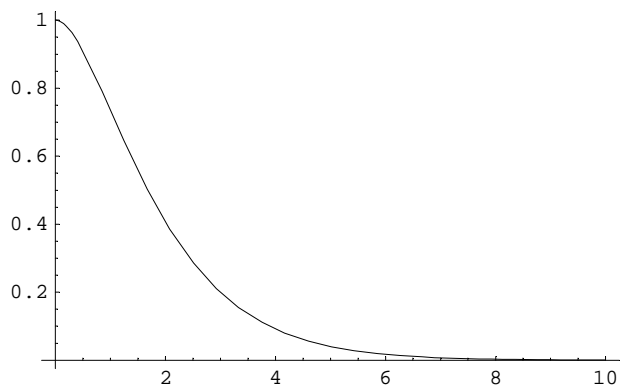
```
In[98]:= U[s]:=(U1[s]//Apart)/.Sign[ω]->1
```

```
In[99]:= u0[t]:=InverseLaplaceTransform[U[s],s,t]//Simplify; u0[t]
```

```
Out[99]=  $e^{-t} (1 + t)$ 
```

```
In[100]:=
```

```
Plot[u0[t],{t,0,10}];
```



o3

1. Linke Seite transformieren, Anfangswerte anpassen

```
In[101]:=
links = LaplaceTransform[1 y''[t]+ 2q y'[t]+ω0^2 y[t],t,s] /.
{LaplaceTransform[y[t],t,s]→Y[s],y[0]→1,y'[0]→0,q→1/2, ω0→1}
```

```
Out[101]=
-1 - s + Y[s] + s Y[s] + s2 Y[s]
```

2. Rechte Seite transformieren

```
In[102]:=
rechts=LaplaceTransform[0 ,t,s]
```

```
Out[102]=
0
```

3. Gleichung links = rechts lösen

```
In[103]:=
solv=Solve[links==rechts,{Y[s]}] // Flatten
```

```
Out[103]=
{Y[s] →  $\frac{1+s}{1+s+s^2}$ }
```

4. Rücktransformation

```
In[104]:=
U1[s]:=Y[s]/. solv; U1[s]
```

```
Out[104]=
 $\frac{1+s}{1+s+s^2}$ 
```

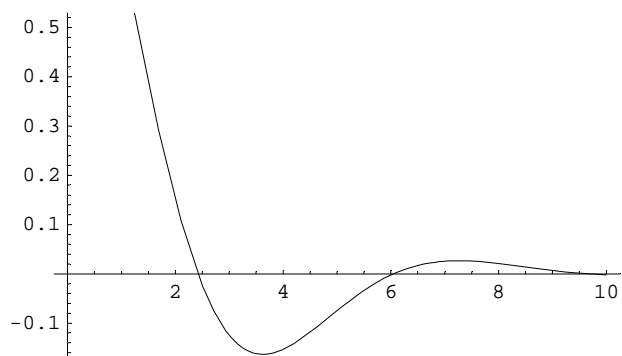
```
In[105]:=
U[s]:=(U1[s]//Apart)/.Sign[ω]->1
```

```
In[106]:=
u0[t_]:=InverseLaplaceTransform[U[s],s,t]//Simplify; u0[t]
```

```
Out[106]=
 $\frac{1}{3} e^{-t/2} \left( 3 \operatorname{Cos}\left[\frac{\sqrt{3} t}{2}\right] + \sqrt{3} \operatorname{Sin}\left[\frac{\sqrt{3} t}{2}\right] \right)$ 
```

In[107]:=

```
Plot[u0[t],{t,0,10}];
```



p

Eigene Experimente....

q

In[108]:=

```
Remove["Global`*"]
```

1. Linke Seite transformieren, Anfangswerte anpassen

In[109]:=

```
links = LaplaceTransform[1 y''[t]+ 2*1 y'[t]+2^2 y[t],t,s] /.
{LaplaceTransform[y[t],t,s]→Y[s],y[0]→1,y'[0]→0}
```

Out[109]=

$$-s + 4 Y[s] + s^2 Y[s] + 2 (-1 + s Y[s])$$

2. Rechte Seite transformieren

In[110]:=

```
rechts=LaplaceTransform[Sin[ω t] ,t,s]/.Sign[ω]->1
```

Out[110]=

$$\frac{\sqrt{\omega^2}}{s^2 + \omega^2}$$

3. Gleichung links = rechts lösen

In[111]:=

```
solv=Solve[links==rechts,{Y[s]}] // Flatten
```

Out[111]=

$$\left\{ Y[s] \rightarrow \frac{2 s^2 + s^3 + 2 \omega^2 + s \omega^2 + \sqrt{\omega^2}}{(4 + 2 s + s^2) (s^2 + \omega^2)} \right\}$$

4. Rücktransformation

In[112]:=

```
U[s]:=Y[s]/. solv; U[s]
```

Out[112]=

$$\frac{2 s^2 + s^3 + 2 \omega^2 + s \omega^2 + \sqrt{\omega^2}}{(4 + 2 s + s^2) (s^2 + \omega^2)}$$

In[113]:=

```
u0[t_]:=InverseLaplaceTransform[U[s],s,t]//Simplify; u0[t]
```

Out[113]=

$$\frac{1}{3 \omega (16 - 4 \omega^2 + \omega^4)} \left(e^{-t} \left(3 \omega (-4 \omega^2 + \omega^4 + 2 (8 + \sqrt{\omega^2})) \right) \text{Cos}[\sqrt{3} t] - 6 e^t \omega \sqrt{\omega^2} \text{Cos}[t \omega] + 16 \sqrt{3} \omega \text{Sin}[\sqrt{3} t] - 4 \sqrt{3} \omega^3 \text{Sin}[\sqrt{3} t] + \sqrt{3} \omega^5 \text{Sin}[\sqrt{3} t] - 2 \sqrt{3} \omega \sqrt{\omega^2} \text{Sin}[\sqrt{3} t] + \sqrt{3} \omega^3 \sqrt{\omega^2} \text{Sin}[\sqrt{3} t] + 12 e^t \sqrt{\omega^2} \text{Sin}[t \omega] - 3 e^t (\omega^2)^{3/2} \text{Sin}[t \omega] \right)$$

5. Konstant schwingender Term isolieren, herausrechnen, Plot der Amplitude als Funktion der Frequenz

In[114]:=

```
coll=Collect[Evaluate[u0[t]/.{Sin[ω t]->x,Sin[Sqrt[3] t]->x^2,Cos[ω t]->x^3,Cos[Sqrt[3] t]->x^4}],{x,x^2,x^3,x^4}];
coll
```

Out[115]=

$$-\frac{2 x^3 \sqrt{\omega^2}}{16 - 4 \omega^2 + \omega^4} + \frac{e^{-t} x^2 (16 \sqrt{3} \omega - 4 \sqrt{3} \omega^3 + \sqrt{3} \omega^5 - 2 \sqrt{3} \omega \sqrt{\omega^2} + \sqrt{3} \omega^3 \sqrt{\omega^2})}{3 \omega (16 - 4 \omega^2 + \omega^4)} + \frac{e^{-t} x (12 e^t \sqrt{\omega^2} - 3 e^t (\omega^2)^{3/2})}{3 \omega (16 - 4 \omega^2 + \omega^4)} + \frac{e^{-t} x^4 (-4 \omega^2 + \omega^4 + 2 (8 + \sqrt{\omega^2}))}{16 - 4 \omega^2 + \omega^4}$$

In[116]:=

```
col2=((coll)/.{x->Sin[ω t],x^2->Sin[Sqrt[3] t],x^3->Cos[ω t],x^4->Cos[Sqrt[3] t],Sqrt[ω^2]->ω})//Cancel
```

Out[116]=

$$\frac{e^{-t} (16 + 2 \omega - 4 \omega^2 + \omega^4) \text{Cos}[\sqrt{3} t]}{16 - 4 \omega^2 + \omega^4} - \frac{2 \omega \text{Cos}[t \omega]}{16 - 4 \omega^2 + \omega^4} + \frac{e^{-t} (16 - 2 \omega - 4 \omega^2 + \omega^3 + \omega^4) \text{Sin}[\sqrt{3} t]}{\sqrt{3} (16 - 4 \omega^2 + \omega^4)} - \frac{(-4 + \omega \sqrt{\omega^2}) \text{Sin}[t \omega]}{16 - 4 \omega^2 + \omega^4}$$

In[117]:=

```
col3 = col2/. {E^(-t)->0, Sqrt[ω^2]->ω}
```

Out[117]=

$$-\frac{2 \omega \text{Cos}[t \omega]}{16 - 4 \omega^2 + \omega^4} - \frac{(-4 + \omega^2) \text{Sin}[t \omega]}{16 - 4 \omega^2 + \omega^4}$$

In[118]:=

```
col4 = col3/. {Cos[ω t]->1, Sin[t ω]->0}
```

Out[118]=

$$-\frac{2 \omega}{16 - 4 \omega^2 + \omega^4}$$

```
In[119]:=
col5 = col3/. {Cos[ω t]->0, Sin[t ω]->1}
```

```
Out[119]=

$$-\frac{-4 + \omega^2}{16 - 4\omega^2 + \omega^4}$$

```

```
In[120]:=
cω1 = col4/Sqrt[col4^2+col5^2]//Simplify
```

```
Out[120]=

$$-2\omega\sqrt{\frac{1}{16 - 4\omega^2 + \omega^4}}$$

```

```
In[121]:=
cω2 = col5/Sqrt[col4^2+col5^2]//Simplify
```

```
Out[121]=

$$-(-4 + \omega^2)\sqrt{\frac{1}{16 - 4\omega^2 + \omega^4}}$$

```

```
In[122]:=
schwing = -(Sqrt[col4^2+col5^2](Sin[α] Cos[ω t]+Cos[α] Sin[t ω])//Simplify)/.
α->ArcSin[cω1]
```

```
Out[122]=

$$-\sqrt{\frac{1}{16 - 4\omega^2 + \omega^4}}\sin\left[t\omega - \text{ArcSin}\left[2\omega\sqrt{\frac{1}{16 - 4\omega^2 + \omega^4}}\right]\right]$$

```

```
In[123]:=
am1=-Sqrt[col4^2+col5^2]//Simplify
```

```
Out[123]=

$$-\sqrt{\frac{1}{16 - 4\omega^2 + \omega^4}}$$

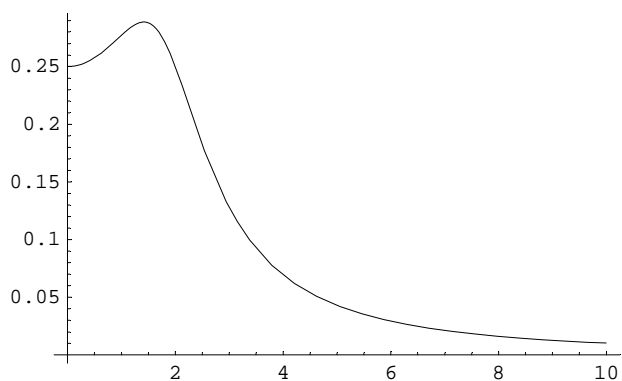
```

```
In[124]:=
am1//InputForm
```

```
Out[124]//InputForm=
-Sqrt[(16 - 4*ω^2 + ω^4)^(-1)]
```

```
In[125]:=
amplitude[ω]:=1/Sqrt[16 - 4*ω^2 + ω^4]
```

```
In[126]:=
Plot[amplitude[ω],{ω,0,10}];
```



```
In[127]:=
  Solve[D[amplitude[x],x]==0,{x}]
```

```
Out[127]=
  {{x -> 0}, {x -> -sqrt[2]}, {x -> sqrt[2]}}
```

```
In[128]:=
  N[%]
```

```
Out[128]=
  {{x -> 0.}, {x -> -1.41421}, {x -> 1.41421}}
```

6. Bemerkung: Die Amplitudenformel gibt dasselbe Resultat:

```
In[129]:=
  Sqrt[2^2-2*1^2]/N
```

```
Out[129]=
  1.41421
```